Project Highclere Cable Details and Installation Method

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Overview

Vocus is proposing to install and operate an offshore fibre optic cable and supporting components (Project Highclere). Project Highclere will form part of Vocus' fibre optic cable network connecting the existing North West Cable System (NWCS) and Australia Singapore Cable (ASC). The Proposed Action includes the installation and operation of the infrastructure only. The geophysical survey component of the Project was the subject of EPBC 2021/9023 which was deemed to be not a controlled action in August 2021 and has been completed without incident.

The Proposed Action includes:

- Installation of new cable to connect the existing NWCS to the existing ASC. This route will run from an
 existing stub cable of the NWCS (approximately 41 km north of Port Hedland) to an offshore existing
 branching unit of the ASC (approximately 450 km west of the Exmouth Peninsula).
- Installation of two branching units and two cables from the new cable to the edge of the petroleum safety zone of the proposed Scarborough Development, approximately 375km west of the Peninsula. The connection of the cable to the Scarborough infrastructure is not in the scope of this referral.
- Installation of two Cable Termination Assemblies (CTA) at the cable ends in close proximity to the Scarborough Development.
- Installation of a branching unit and 'stub' to allow for a future potential connection.
- Operation of the cable.

Figure 1 below shows the location of the proposed cable including the cable paths to the Scarborough Development.

Schedule

Installation of the cable is currently planned to commence in late Q4 2022 and will take ~ 60 days. Commissioning and testing of the cable is expected to take up to 2 months. The design life for the cable is ~25 years. Another mobilisation will occur in ~18 months or later for the installation of the two CTAs.

Cable details

The main cable route is 1025 km long and the Scarborough connection route is 69 km long. Installation accuracy will vary depending on depth. A 100 m buffer has been nominated on each side of the planned cable route to account for the inherent cable lay accuracy due to the water depths in which the cable will be laid. The cable will be laid as close as possible to the centre line.

Various Alcatel-Lucent cable types will be used. The diameter of the cable will vary between 14.0 mm to 35 mm along the cable length. The cable width is determined by the level of armoring that is applied, which in turn is determined by the depth of the water, risks to the cable and seabed type where the cable section is being laid. The cable will carry an electrical charge of up to 5000 volts (DC). The cable is surrounded by conductive and protective material and does not generate any electric field external to the cable. A description of the cable type is provided in Figure 2.

Installation

The cable laying will be conducted by the IIe de Re IMO: 8200278. This vessel deploys a cable burial sea plough ROV to assist cable deployment and other maintenance activities. The vessel power capacity is 10,500 KW and it has IMO dynamic positioning class 2 to assist the accuracy of cable deployment activities. Vessel specifications are provided as Figure 3.

Prior to cable lay, a clearance operation will be undertaken to remove debris along the route. This will be conducted by a Pre-Lay Grapnel Run (PLGR) which involves towing a grapnel device along the seafloor to remove marine debris from the route. Towing speeds will be approximately 1.5 km/hr. A PLGR will only be conducted within areas where the cable is planned to be buried. This method is not designed for deep penetration into the seabed. The method will be to launch the grapnel and pay out a towing line scope appropriate to the depth of water. The towing line is passed over a sensitive tension measurement device which is monitored continuously. Changes in recorded tension may indicate that debris has been encountered. The grapnel is recovered, and any debris cleared and retained on board for safe disposal onshore. The grapnel array is then redeployed.

In water depths up to 1000 m the cable will be buried to provide extra protection and stabilisation. This will be achieved via a means such as ploughing or post lay burial via jetting, dependent on location. Where plough or post lay burial is not possible due to seabed type, the cable will be directly laid on the seabed. In water depths deeper than 1000m, the cable will be laid directly on the seabed. A illustration of the cable lay technique and example plough system is provided in Figure 4.

Plough burial can be undertaken simultaneously to the laying of the cable and will be used where sufficient suitable sediment exists in waters up to 1000 m water depth. As the plough is lowered to the seafloor and pulled along by the vessel, the cable is simultaneously threaded through the plough. The plough creates a narrow trench approximately 200 mm wide into which it places the cable before burying it. Target cable depth for deployment by plough is 1m. Where sufficient sediment does not exist, target burial depth will be reduced. In other areas where ploughing is not possible, such the approach to branching units or pipeline crossing, a ROV using jetting techniques will be used to bury the cable.

The proposed cable route will cross an existing flowline associated with the Scarborough Development using standard installation techniques. The use of protective material between the flowline and cable is still to be determined. A solid polyurethane material is being assessed.

The CTA equipment will be installed by craning from a vessel with ROV assistance. This equipment is small in size (height = 3m) and includes a mud mat ($3m \times 3m$), frame, cable connection module and cable leads for connection by others at a later date. Details of the CTA is provided in figure 5.

Commissioning, Operation and Maintenance

Commissioning of the new infrastructure including final network testing is expected to take 1-2 months post completion of installation. Operation of the cable will be managed remotely via the Proponent's existing operations centre in Melbourne. Once installed, it is not expected that the cable network will require any routine maintenance. In the event of damage or failure of the cable, relevant authorities and stakeholders will be consulted. In this case, it is likely that repairs will involve hauling the cable to the surface for repair.

Decommissioning

The life of the cable is a ~25 years and removal of the decommissioned cable is not considered feasible as:

- The potential environmental impacts of the retrieval and disposal of 1,094 km of buried cable are likely to significantly outweigh the impacts of leaving an inert cable in place.
- The commercial cost of retrieval and disposal of 1,094 km of cable are likely to significantly affect the commercial viability of the Project.
- Developing technology may extend the life of the cable or lead to recommissioning of the cable being a viable option.

Customer connections

The Proposed Action does not include connection to the Scarborough Development which would be via a 130 m cable from the CTA to the Development connected via ROV with little seabed disturbance. Requirements for this connection will be managed either by the Proponent or the Customer.

Figure 1. Proposal Location



Project Highclere Cable Route



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- WA State Waters Boundary
- ASC National Marine Parks
- --- Highclere Cable Route 🛛 🔲 Key Ecological Feature



PERTH



This map has been compiled with data from numerous sources with different levels of accuracy and reliability and is considered by the authors to be fit for its intended purpose at the time of publication.

However, it should be noted that the information shown may b subject to change and ultimately, map users are required to determin the suitability of use for any particular purpose.

JACOBS does not warrant that this map is free from errors or omissions. JACOBS shall not be in any way liable for loss, damage or nigury to the user of this map or any other person or organisation consequent upon or incidental to the existence of errors or omissions Figure 2. Description of Cable

The cross section to the right shows a lightweight protected cable that will be utilised in water depths greater than 700 m for surface lay activities. The lightweight cable includes a metallic screen and polyethylene outer jacket applied over the core cable for basic protection from moderate abrasion and/or attack by marine life (Alcatel Lucent, 2013a). This method of protection is applied when there are no known risks to the cable from human factors (Worley Parsons, 2011). The external sheath consists of High Density Polyethylene (HDPE) dielectric and the metallic screen protects the cable from electromagnetic emissions (ICPC, 2011).

The cross section to the right shows a single armour cable that will be utilised within the HDD and in water depths up to 700 m. The single armour cable includes a light to heavy armour wire layer (galvanised steel) applied to the core cable, with additional abrasion protection consisting of a PIP yarns (Alcatel Lucent, 2013a). This level of protection also includes a 'flooding compound' that consists of a bituminous based material blended with synthetic polymers for bonding and corrosion protection between the armouring wires and plastic sheath (ICPC, 2011 and H&R ChemPharm Ltd, 2006). This type of protection is applied in areas with a moderate to high risk of trawler damage (Worley Parsons, 2011).



The cross section to the right shows a double armour cable that will be utilised during shallow water lay operations (less than 500 m deep). It consists of the same protective measures applied to the cable core as the previous cable cross section however; it also includes a second armour wire layer. This type of protection is required in areas with a high risk from trawler damage as it substantially reduces the potential for a cable being snagged (Alcatei Lucent, 2013a). It also protects the cable in areas exposed to harsh wave conditions as with the coastline.



Figure 3. Vessel and Plough Specifications



-	SHIP'S PARTICULARS - CABLE SHIP													
	Do	cument to b	e manage	ed as a cer	tificate (cf.	FO-ALL	-MGT003E)		On	28/11	/2020	By	CAF	PTAIN
Underkeel extension Stern thrusters under keel structure, depth 1.30 m (extension included in aft draft scale)														
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	Jakarta S	elatan, 140	94 - INDO	4 - INDONESIA Tel			(+33) 1 70 38 60 00						MALAYSIA (+60)3-5518 3	388
Tel	(+62) 21	2598 1466			Fax	: (+33) 1	70 99 33 92				Tel		(
Dimensi	ions	LOA		143,400		m	Heigl	ht of ar	ntenna o	on forema	st on BL		32,200	m
LPP			123,000			m	h Height of antenna on wheelhouse on BL 41,960					41,960	m	
Breadth Moulded			20,500			m Height of antenna				on aftma	nast on BL		37,200	m
Extreme Breadth				23,300	m Depth from hanga				ar deck to	o baseline 14,600 m			m	
	De	epth Mouled		14,600		m		Dep	th from	bridge to	baseline		27,75	m
Drafts				Dr	afts		Deadwe	ight		Freel	board		TPC	
	Winter			7,		323 m		260	mt	0,2	272	m	25,3	mt
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	Tropical					m	/		mt		/	m	/	mt
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<u></u>	Diesel G	Generator(s)	2 x WAR	TSILA 9L2	26A - 2 x 2	925 KW a	at 1000 RPN	//2 x	WARTS	SILA 8L20) - 2 x 14	40 KW at	1000 RPM	
		Gear box	500 / 221	1										
		Propeller	Controlla	ble Pitch										
	A	Alternator(s)	Emergen	cy Genera	ator MAN E	02866TF	- 150 KW at	1500	RPM					
	Bow thruster 2 x 1500 KW													
	St	ern thruster	2 x 1500	KW										
Cable E	quipment	<u>.</u>	1 x Crane	e 5T/25m	Hydralift ·	+ 1 x Heila	a Crane 21T	+ 1 x	Heila C	rane 13,5	T + 1 x S	MD A-Fra	ime 35T	
			2 x Drum	s Cables I	Engines 25	5 T + 2 x [OOHB 6T							
			3 x Trans	sporters 27	Γ									
			2 x Tugger winches 10T + 1 Tow winch 60T											
			1 x BOV/ Perry Slingshy Systems Triton ST206 + 1 x 2M/3M Plough Gamma ungraded											
			3 x MainTanks 4100mT + 3 x Spare Tanks 600mT											
Anchori	na & Moo	orina	2 x Anch	or Canstar	ns 160kN -	+ 4 x Moo	ring winche	s 80kN						
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SMD Heavy Duty HD3 Plough Ploughs Technical Specifications GENERAL SPECIFICATION AND OPERATION DIMENSIONS 10.82 10.82 m long (skids down, plough hinged, depressor down) 4.80 m high (plough hinged) 5.96 m wide (over rear stabilisers) SUBMERGED WEIGHT OPERATION 25 tonnes (excluding ripper and jetting package) Pulled by tow wire from surface vessel Full remote control from shipboard control cabin or from remote control console whilst being towed CONTROL $^{+/-}$ 16° 2.30 m trench depth at zero share pitch (soil dependent) 3.00 m achievable in soft soils with plough pitched aft Optional interchangeable share 1.5 m available STEER ANGLE **BURIAL DEPTH** A forward mounted Rock Tooth can cut the trench in rock usually with a layer of soil above it OPERATING DEPTH 1500 m maximum REPEATER BURIAL SOIL TYPE SOFT MUD CAPACITY PLOUGHING SPEED HYDRAULIC SYSTEM Repeater burial depth 50-90% of plough burial depth, dependent on soil conditions Any, within limits of pull force (130 tonnes) 5 kPa minimum Recommended maximum 2 knots depending on seabed conditions RESERVOIR: Flexible pressure compensated, 100 litres working capacity SYSTEM HYDRAULIC OIL: Houghton Vaughan Hydrodrive HPE 22 Heavy duty marine type with welded swivel eyes **CYLINDERS** SURVEILLANCE EQUIPMENT The surveillance equipment comprises CCTV cameras, associated lamps, pan and tilt units CAMERAS 3 x ST LAMPS: 5 x 150 W 24 V incandescent SONAR: Mesotech 1000 digital sonar head (range up to 100 m) HVDROPHONE: A hydrophone is provided with an integral pre-amplifier SONAR: DOSTINUES DESCRIPTION (range up to 100 m) ACOUSTIC POSITIONING: Provision is made for responder/ transponder unit D JAN 2013 ALCATEL-LUCENT Alcatel Lucent

Figure 4. illustration of the cable lay technique and example plough system



Illustration of Cable Lay Technique (Source - www.makai.com)



Example Plough System

Figure 5. CTA Design

